

# Chemical Engineering 374

*Fluid Mechanics*  
*Fall 2011*

Computational Fluid Dynamics  
(CFD)



1

## So far...

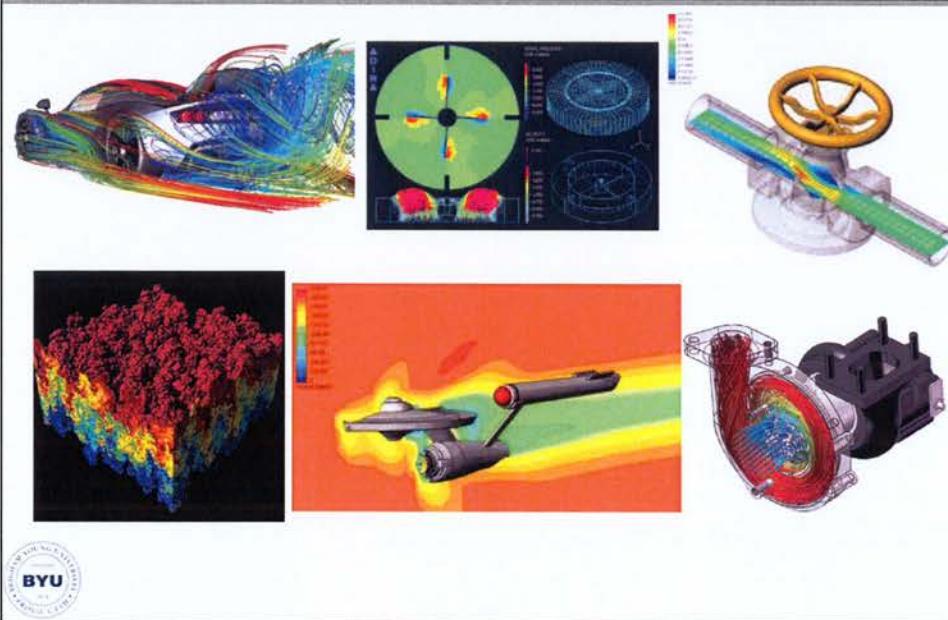
- Fluid statics (no flow)
- Basic flows: Bernoulli Equation
- Integral Balances: Control volume → mass, momentum, energy
- Differential Balances → momentum and mass (Navier Stokes)
- All of this was for
  - Simple configurations that we could directly solve analytically
  - 0-D, or 1-D
  - Steady State
  - Incompressible
- 2D or 3D flow in complex geometry, or turbulent, or compressible, are too complex for analytic solution
  - → Solve with computers
- Big Subject → give a basic introduction



2

## Examples

3



## Key Aspects

4

- Governing equations
- Mathematical description
- Grid generation
- Numerical algorithm
- Turbulence modeling
- Convergence
- Stability
- Verification
- Validation

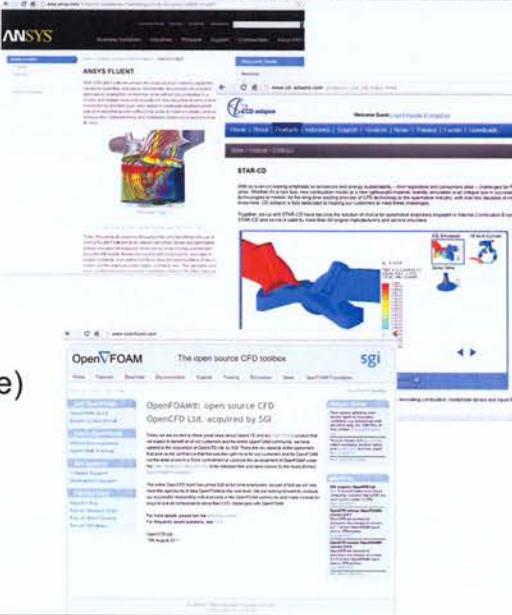


2

## Software

5

- Commercial
  - Ansys Fluent
  - CD-Adapco—Star CD
- Free
  - OpenFOAM
  - Free CFD
- In-house codes
  - (everyone's got one)
- Many others
  - [www.cfd-online.com](http://www.cfd-online.com)



## Nuts and Bolts

6

- Most of CFD boils down to the following
- Create a spatial grid for the solution
  - Finite difference → grid of points
  - Finite volume → grid of connected 0-D control volumes
- Here focus on finite difference
  - Approximate the derivatives using the grid points.
    - 1 PDE → many coupled ODE's, one for each point.
    - Solve the system of ODE's at each grid point.



①

## Example 1

Unsteady, Laminar Pipe flow, 1-D

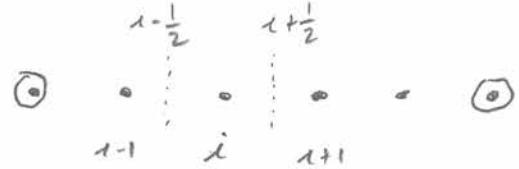
X-momentum

$$\rho \left( \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} \right) = - \frac{\partial p}{\partial x} + \rho f_x + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

- $\frac{\partial u}{\partial t} = \frac{\mu}{\rho} \frac{\partial^2 u}{\partial x^2} - \frac{1}{\rho} \frac{\partial p}{\partial x}$

- Grid of Points across D

$$\Delta x = \frac{D}{N-1}$$



- $\left( -\frac{1}{\rho} \frac{\partial p}{\partial x} \right)$  is a constant.

- Approximate  $\frac{\partial^2 u}{\partial x^2}$  at each point i

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} \right) \approx \underbrace{\frac{\left( \frac{\partial u}{\partial x} \right)_{i+1/2} - \left( \frac{\partial u}{\partial x} \right)_{i-1/2}}{\Delta x}}_{\left( \frac{\partial u}{\partial x} \right)_{i+1/2} \approx \frac{u_{i+1} - u_i}{\Delta x}}$$

$$\left( \frac{\partial u}{\partial x} \right)_{i-1/2} \approx \frac{u_i - u_{i-1}}{\Delta x}$$

$$\left( \frac{\partial^2 u}{\partial x^2} \right)_i \approx \frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta x^2}$$

- $\frac{\partial u_i}{\partial t} = \frac{\mu}{\rho} \left( \frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta x^2} \right) - \frac{1}{\rho} \frac{\partial p}{\partial x}$  for interior  $i=2, N-1$

- $u_1 = 0, u_N = 0$  at B.C.

- PDE  $\rightarrow$  N-2 ODE's (coupled)

Now Solve These ODE's.

- Use your favorite ODE solver.
- Or use Explicit Euler:

$$\frac{du}{dt} = f(u) \rightarrow \frac{u^{n+1} - u^n}{\Delta t} = f(u^n)$$

$$\rightarrow u^{n+1} = u^n + \Delta t \cdot f(u^n)$$

So, for us:

$$u_i^{n+1} = u_i^n + \frac{\Delta t \mu}{P \Delta x^2} (u_{i+1}^n - 2u_i^n + u_{i-1}^n) - \frac{1}{P} \frac{\partial P}{\partial x} \cdot \Delta t$$

Solve in Excel. See Attached

Now, in 2-D its very similar,

Grid

$$\begin{array}{cccccc} \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \end{array} \quad \frac{\partial^2 u}{\partial x^2} \rightarrow \begin{array}{cccccc} \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \textcircled{u} & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \end{array}$$

$$\frac{\partial^2 u}{\partial y^2} \rightarrow \begin{array}{cccccc} \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \textcircled{u} & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \end{array}$$

Have  $\frac{\partial u_i}{\partial t} = f(u, v, P \text{ on the grid})$

$\frac{\partial v_i}{\partial t} = f(u, v, P \text{ on the grid})$

Solve with ODE solver.

### Example 2

2-D unsteady Laminar Jet

3 eqns in 3 unknowns  $u, v, P$

Cont:  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \quad = \nabla \cdot \vec{v} = 0$

\* x-mom:  $\rho \left( \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right) = - \frac{\partial P}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$

\* y-mom:  $\rho \left( \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right) = - \frac{\partial P}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$

- x-mom is the  $u$  eqn
- y-mom is the  $v$  eqn
- but where is the  $P$  eqn? Continuity?

Get a  $P$  eqn by taking  $\nabla \cdot$  mom eqn, and inserting continuity

$$\rightarrow \nabla \cdot \nabla P = -\frac{1}{\rho} \nabla \cdot (\vec{v} \cdot \nabla \vec{v})$$

- 
- Discretize in Space, Solve in Time.

Boundary conditions.

- Walls:  $u = v = 0$  (or  $u = v = V_{wall}$ )

- Inlet:  $u = U_{in}, v = V_{in}$

- Outlet:  $\frac{\partial u}{\partial x_n} = 0 ; \frac{\partial v}{\partial x_n} = 0$

-Recirculation at outlets is a problem!  $\rightarrow$  locate Down Stream

---

See jet code

## Other Issues.

- Last examples were incompressible.
- When Compressible.
  - Capture Sound Speed  $\rightarrow$  Small timesteps
  - Solve an Energy equation too
  - $\rho = \frac{MP}{RT} \rightarrow u, v, P, \rho, e$  5 eqns / unknowns
- When Reacting.
  - Solve eqns for  $Y_i$
- When turbulent
  - Have to resolve the turbulence  $\rightarrow$  expensive.
  - or model it (next time)
- Grid Quality
 

+ - . . . + vs + - . . .
- Staggered Grid
- Numerical Diffusion
- etc.
- Many issues Discussed in Detail in CHEn 541.

## Turbulent Flows.

Turbulence is 3D

Unsteady

Chaotic

Has a range of length  $\Rightarrow$  time scales,

To get enough grid points to resolve the structure is expensive computationally.

Cost scales as  $Re^3$ , so Doubling the Domain Size ( $2 \times 2c$ )  
 $\rightarrow 8 \times$  The cost (and a bigger domain needs a longer run time)

Resolving Turbulence in CFD is called DNS : Direct Numerical Simulations — Only used in research!

All practical CFD codes model the turbulence.

- Solve for the average flow  $\rightarrow$  RANS  
 (Reynold Average Navier Stokes)
- Only resolve the large eddies, but not the small ones  
 (LES = Large Eddy Simulation)  
 (LES is expensive  $\rightarrow$  mostly research, but way less expensive than DNS)

---

Average the flow equations :  $\bar{\phi} = \frac{1}{T} \int_0^T \phi dt$  when  $\phi$  is some quantity, like  $V$ , and  $T$  is a long time,

Decompose  $\mathbf{V}$  into  $\bar{\mathbf{V}} + \mathbf{v}'$  where  $\bar{\mathbf{V}}$  is avg,  $\mathbf{v}'$  is fluctuation. We discussed this before with turbulent pipe flow.

$$\nabla \cdot \mathbf{V} = 0$$

$$\frac{\partial \mathbf{v}}{\partial t} + \nabla \cdot (\mathbf{V}\mathbf{V}) = -\frac{1}{\rho} \nabla P + g + \nabla^2 \mathbf{V}$$

$$\begin{aligned} \frac{\partial \mathbf{v}}{\partial t} &\rightarrow \frac{\partial(\bar{\mathbf{V}} + \mathbf{v}')}{\partial t} \xrightarrow{\text{average}} \frac{\partial}{\partial t} \overline{(\bar{\mathbf{V}} + \mathbf{v}')} \\ &\rightarrow \frac{\partial \bar{\mathbf{V}}}{\partial t} \\ &= \frac{\partial}{\partial t} (\cancel{\bar{\mathbf{V}}} + \cancel{\mathbf{v}'}) \end{aligned}$$

$$\nabla^2 \mathbf{V} \rightarrow \nabla^2 \bar{\mathbf{V}} \quad \text{likewise.}$$

$$\begin{aligned} \nabla \cdot (\mathbf{V}\mathbf{V}) &\stackrel{\text{avg}}{\rightarrow} \nabla \cdot \left( \overline{(\bar{\mathbf{V}} + \mathbf{v}')(\bar{\mathbf{V}} + \mathbf{v}')} \right) \\ &= \nabla \cdot \left( \bar{\mathbf{V}}\bar{\mathbf{V}} + 2\bar{\mathbf{V}}\mathbf{v}' + \mathbf{v}'\mathbf{v}' \right) \\ &= \nabla \cdot \left( \bar{\mathbf{V}}\bar{\mathbf{V}} + \cancel{2\bar{\mathbf{V}}\mathbf{v}'} + \bar{\mathbf{v}}'\bar{\mathbf{v}}' \right) \\ &= \nabla \cdot (\bar{\mathbf{V}}\bar{\mathbf{V}}) + \boxed{\nabla \cdot \bar{\mathbf{v}}'\bar{\mathbf{v}}'} \quad \rightsquigarrow \text{new term.} \end{aligned}$$

$$\nabla \cdot \bar{\mathbf{V}}$$

$$\frac{\partial \bar{\mathbf{V}}}{\partial t} + \nabla \cdot (\bar{\mathbf{V}}\bar{\mathbf{V}}) = -\frac{1}{\rho} \nabla \bar{P} + g + \nabla^2 \bar{\mathbf{V}} + \boxed{\nabla \cdot (\bar{\mathbf{v}}'\bar{\mathbf{v}}')}$$

- we have 2 eqns in 2 unknowns:  $\bar{\mathbf{V}}, \bar{P}$
- but we don't know  $\bar{\mathbf{v}}'\bar{\mathbf{v}}'$  → have to model it.  
This is the challenge of CFD: Finding good models for these terms.
- $\bar{\mathbf{v}}'\bar{\mathbf{v}}'$  is the Reynolds Stress, has units of Stress and is usually modeled as  $\bar{\mathbf{v}}'\bar{\mathbf{v}}' = \mu_t \nabla \cdot \bar{\mathbf{V}}$  where  $\mu_t$  is some modeled turbulent kinematic viscosity.
- The standard model is  $[k-E]$ : The "kay-epsilon model"